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# On the consistency of $X^\top AX = B$ when $B$ is either symmetric or skew

Alberto Borobia    Roberto Canogar    *Fernando De Terán*

Departamento de Matemáticas, Universidad Carlos III de Madrid, Leganés, Spain

In this talk, we analyze the consistency of the matrix equation

$$X^\top AX = B, \tag{1}$$

where  $A \in \mathbb{C}^{m \times m}$ ,  $X \in \mathbb{C}^{m \times n}$  (unknown), and  $B \in \mathbb{C}^{n \times n}$  is either symmetric or skew-symmetric. In particular, we will first provide a necessary condition for (1) to have a solution  $X$ . Then, we will prove that this condition is also sufficient for most matrices  $A$  and an arbitrary symmetric (or skew) matrix  $B$ . To be more precise, we will first show that, in order to analyze the consistency of (1), we can restrict ourselves to the case where  $A$  and  $B$  are in *Canonical form for congruence*. We use the canonical form for congruence introduced in [3], which is a direct sum of blocks of three types. Then, we will show that the condition mentioned above is sufficient when  $A$  does not contain any blocks of some of these types with certain size.

We want to emphasize that the question on the consistency of (1), when  $B$  is symmetric (respectively, skew), is equivalent to the following problem: given a bilinear form over  $\mathbb{C}^n$  (represented by the matrix  $A$ ), find the maximum dimension of a subspace such that the restriction of the bilinear form to this subspace is a symmetric (resp., skew) non-degenerate bilinear form.

The results presented in this talk for  $B$  being symmetric have been published in [1], whereas the ones for  $B$  being skew-symmetric are contained in the submitted manuscript [2].

## References

- [1] A. Borobia, R. Canogar, F. De Terán, *On the consistency of the matrix equation  $X^\top AX = B$  when  $B$  is symmetric*, *Mediterr. J. Math.*, (2021) pp. 18-40.
- [2] A. Borobia, R. Canogar, F. De Terán, *The equation  $X^\top AX = B$  with  $B$  skew-symmetric: How much of a bilinear form is skew-symmetric?*, submitted (2021).
- [3] R. A. Horn, V. V. Sergeichuk. *Canonical forms for complex matrix congruence and \*-congruence*, *Linear Algebra Appl.*, 216 (2006) pp. 1010-1032.