

Estimates on the Cheeger constant

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Isoperimetric problems

Pisa



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Anisotropic isoperimetric problems & related topics

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Rome (IT)

The workshop aims at bringing together experts and young researchers working in the field of anisotropic isoperimetric problems, with a particular focus on the following subjects:

- (A) Isoperimetric problems with density;
- (B) Crystals and periodic structures;
- (C) Gamow liquid drop model;
- (D) Isoperimetric problems in geometric structures;
- (E) Spectral problems.

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The Cheeger problem

Let $\Omega \subset \mathbb{R}^N$. The *Cheeger constant* of Ω is defined as

$$h(\Omega) := \inf \left\{ \frac{P(E)}{|E|}, E \subset \Omega, |E| > 0 \right\},$$

where $P(E)$ denotes the distributional perimeter of the Borel set E , and $|E|$ the standard N -dimensional Lebesgue measure.

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Why do we care?

Spectral applications:

(i) lower bounds to the first eigenvalue of the p -Laplacian

$$\left(\frac{h(\Omega)}{p}\right)^p \leq \lambda_p(\Omega);$$

(ii) if Ω is “good enough”, $h(\Omega) = \lambda_1(\Omega)$;

(iii) estimates on the L^1 norm of the p -torsion function w_p

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(iv) it acts as **threshold for the existence of non trivial minimizers** of

$$P(E) - \kappa|E|, \quad \text{among } E \subset \Omega,$$

since one needs $\kappa \geq h(\Omega)$;

(v) it acts as **threshold for the existence of solutions** of

$$\operatorname{div} \frac{\nabla u(x)}{\sqrt{1 + |\nabla u(x)|^2}} = H, \quad x \in \Omega,$$

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(vi) the Cheeger constant of the square even appeared in an elementary proof of the Prime Number Theorem..

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Robustness of the relations

Most of these relations hold in very general spaces. Given a **metric measure space** $(X, \mathcal{B}, \mathfrak{m})$, and $P(\cdot)$ the **perimeter induced by the metric**, one can define for $\Omega \subset X$

$$h(\Omega) := \inf \left\{ \frac{P(E)}{\mathfrak{m}(E)}, E \subset \Omega, \mathfrak{m}(\Omega) > 0 \right\}.$$

If $(X, \mathcal{B}, \mathfrak{m})$ is “good” **one retains the spectral relations** we mentioned.

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Today's plan

Today we shall zero-in on the easiest possible framework, that of the **Euclidean N -dimensional space**, for an open, and bounded set Ω .

A brief overview of our tour:

- 1) we start in **dimension $N = 2$** ;
- 2) we pass to estimates for **cylindrical sets**;
- 3) we conclude with **quantitative estimates**.

$N = 2$: convex sets and strips

Given $\Omega \subset \mathbb{R}^2$ its “inner parallel set” at distance t is

$$\Omega^t := \{x \in \Omega : \text{dist}(x, \partial\Omega) \geq t\}.$$

Let Ω be **convex** [Kawohl & Lachand-Robert (2006)] or a **strip** [Leonardi & Pratelli (2016)]. Then, Ω has a **unique Cheeger set** E given by

$$E = \bigcup_{x \in \Omega^r} B_r(x),$$

where $r = 1/h(\Omega)$. Moreover, the **inner Cheeger formula** holds: r is the unique positive solution of

$$\pi r^2 = |\Omega^r|.$$

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$N = 2$: sets w/no necks

Definition

A set Ω has no “necks” of radius r if the following holds. Given two balls of radius r , $B_r(x_0)$ e $B_r(x_1)$ contained in Ω , there exists a continuous curve $\gamma : [0, 1] \rightarrow \Omega$, such that

$$\gamma(0) = x_0, \quad \gamma(1) = x_1, \quad \text{and} \quad B_r(\gamma(t)) \subset \Omega, \quad \forall t \in [0, 1].$$

Theorem (Leonardi, Neumayer, S. (2017) & Leonardi, S. (2020))

Let Ω be a Jordan domain such that $|\partial\Omega| = 0$, and let r be the unique positive solution of $\pi t^2 = |\Omega^t|$. If Ω has no necks of radius r , then

$$h(\Omega) = \frac{1}{r}, \quad \text{and} \quad E = \bigcup_{x \in \Omega^r} B_r(x),$$

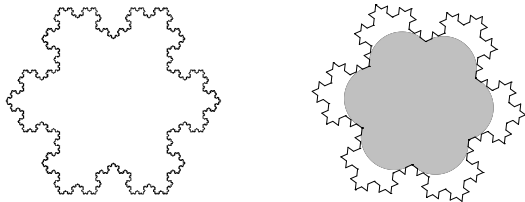
is the maximal Cheeger set of Ω .

An unfortunate example

The theorem in principle is great. It gives a formula to compute the constant and a recipe to find a Cheeger set. At times though..

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A Koch snowflake has no necks of any size, thus the inner Cheeger formula holds. Yet, this is not algebraically solvable.

Approximating $h(\Omega)$

We have an error estimate of $h(\Omega)$ w.r.t. interior approximations.

Proposition (Leonardi, Neumayer, S. (2017))

Let ω, Ω be open sets in \mathbb{R}^2 such that $\omega \subset \Omega$. Let $r = h^{-1}(\omega)$ and $R = h^{-1}(\Omega)$ and assume the inner Cheeger formula holds for both ω, Ω , i.e., $|\omega^r| = \pi r^2$ and $|\Omega^R| = \pi R^2$. Then,

$$0 \leq R - r \leq \frac{|\Omega^r \setminus \omega^r|}{2\pi r}.$$

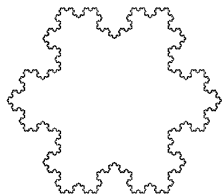
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Computing r_n for the approximating sets is easy. The error is

$$0 \leq r_\infty - r_n \leq \frac{2^{n-3}}{25 \cdot 3^{3n-5}}.$$

Estimates for cylindrical sets

Fix the cylinder $\Omega \subset \mathbb{R}^{N+1}$ w/cross section $\omega \subset \mathbb{R}^N$ & height $L > 0$

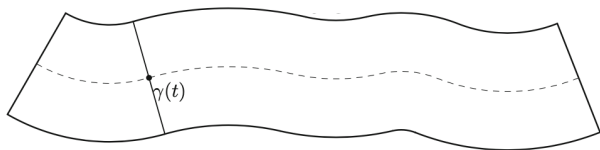
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If $N = 1$, cylinders are rectangles, which we got covered. Similarly to rectangles, one can consider “strips” [Krejčířik & Pratelli (2011)],

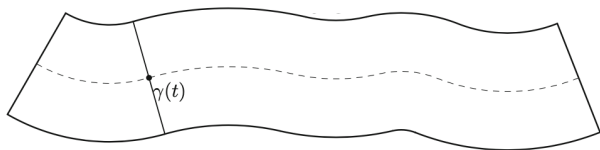


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and have (here ω is a segment $[0, \ell]$)

$$h(\omega) + \frac{1}{400} \frac{1}{L} \leq h(\Omega) \leq h(\omega) + \frac{2}{L}.$$

A second order improvement came with [Leonardi & Pratelli (2016)].

Estimates for cylindrical sets

Similar estimates hold for general N -dimensional cross section $\omega \subset \mathbb{R}^N$.

Theorem (Pratelli, S. (forthcoming))

Let $\Omega = \omega \times [0, L]$ w/cross section $\omega \subset \mathbb{R}^N$ & height $L > 0$. *There exists a constant $c = c(\omega) > 0$, such that*

$$h(\omega) + \frac{c}{L} \leq h(\Omega) \leq h(\omega) + \frac{2}{L}.$$

The constant c only depends on the volume of ω 's “smallest” Cheeger set.

An application

Let $p > 1$, and let $F_{p,1}$ be the shape functional

$$F_{p,1}[E] := \frac{\lambda_p(E)}{h^p(E)}.$$

defined over \mathcal{K}^N , the class of convex subsets of \mathbb{R}^N .

Theorem (Pratelli, S. (forthcoming))

There exist minima of $F_{p,1}$ in \mathcal{K}^N , in any dimension N .

This positively solves a conjecture by [Parini (2017)] (for $p = 2$) and by [Briani, Buttazzo, Prinari (2021)], exploiting the estimates for cylindrical sets and tools proved in [Ftouhi (2021)].

Quantitative estimates

Let us recall the **isoperimetric quantitative inequalities**. Given any set Ω , we let B_Ω be the ball with its same volume. We have

$$\begin{aligned} \text{(i)} \quad & \frac{P(\Omega) - P(B_\Omega)}{P(B_\Omega)} \geq 0, & \text{(iii)} \quad & \frac{P(\Omega) - P(B_\Omega)}{P(B_\Omega)} \geq c\zeta(\Omega), \\ \text{(ii)} \quad & \frac{P(\Omega) - P(B_\Omega)}{P(B_\Omega)} \geq c\alpha^2(\Omega), & \text{(iv)} \quad & \frac{P(\Omega) - P(B_\Omega)}{P(B_\Omega)} \geq c\beta^2(\Omega), \end{aligned}$$

where $\alpha(\Omega)$, $\zeta(\Omega)$ and $\beta(\Omega)$ are asymmetry indexes, measuring the distance in some suitable sense of Ω from an optimal set.

Can one obtain the analog with $h(\cdot)$ in place of $P(\cdot)$?

Quantitative estimates

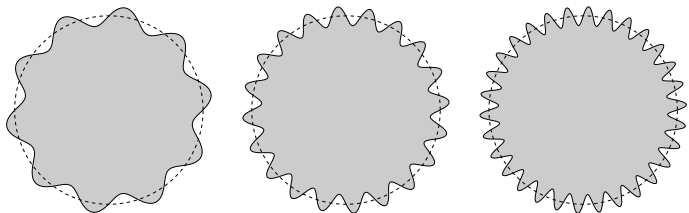
The analogue of (i) is an immediate consequence of (i) itself, while the analogue of (ii) has been proved in [Figalli, Maggi, Pratelli (2009)].

Theorem (Julin, S. (2021))

Given $\Omega \subset \mathbb{R}^N$ open and bounded. *There exists $c = c(N)$ such that*

$$\frac{h(\Omega) - h(B_\Omega)}{h(B_\Omega)} \geq c\zeta(\Omega).$$

It does not exist $c = c(N)$ s.t. the inequality with β^2 in place of ζ holds.



Quantitative Gaussian estimates

We have also proved **similar estimates in the Gaussian space**, where the volume and the perimeter are weighted by the Gaussian measure γ .

Theorem (Julin, S. (2021))

Given $\Omega \subset \mathbb{R}^N$ open and bounded. There exist $c_1 = c_1(\gamma(\Omega))$ such that

$$h_\gamma(\Omega) - h_\gamma(H_\Omega) \geq c_1 \alpha_\gamma^2(\Omega).$$

and $c_2 = c_2(\gamma(\Omega))$ such that

$$h_\gamma(\Omega) - h_\gamma(H_\Omega) \geq c_2 \frac{\beta_\gamma(\Omega)}{1 + \sqrt{|\log(\beta_\gamma(\Omega))|}}.$$

References

- Julin, V. and Saracco, G., Quantitative lower bounds to the Euclidean and the Gaussian Cheeger constants, *Ann. Fenn. Math.* 46:2, 2021
- Leonardi, G. P., Neumayer, R. and Saracco, G., The Cheeger constant of a Jordan domain without necks, *Calc. Var. Partial Differential Equations* 56(6):164, 2017
- Pratelli, A. and Saracco, G., *forthcoming*



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