

# Isoperimetric Problems

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Steiner Problem, global and local minimizers of the length functional



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# Structure of the talk

Steiner Problem : classical formulation  
basic properties

Minimal partitions problem : relation with Steiner  
paired calibrations  
a local minimality result

Currents with coefficients in a group : relation with Steiner  
calibrations vs.  $\mathbb{C}$  paired calibrations  
a global minimality result

Łojasiewicz - Simon inequality for minimal networks

# Steiner Problem

Let  $\mathcal{L} = \{p_1, \dots, p_n\}$  be a finite collection of points in  $\mathbb{R}^2$ .

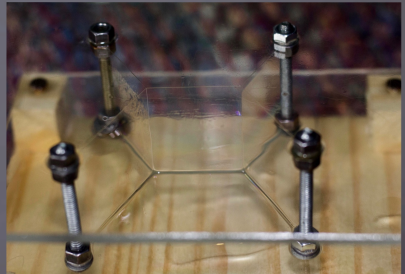
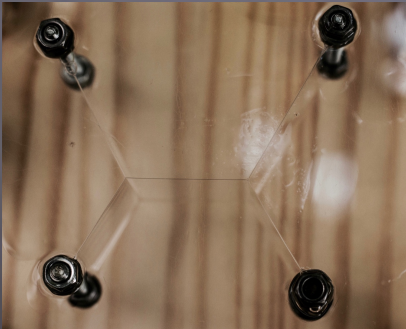
Steiner Problem: Find a connected set  $K$  such that  $\mathcal{L} \subset K$  and the length of  $K$  is minimal

$$\inf \{ \mathcal{H}^1(K) : K \subseteq \mathbb{R}^2, \text{ connected and such } \mathcal{L} \subseteq K \}$$

There exists a minimizer to the Steiner problem

# Steiner Problem

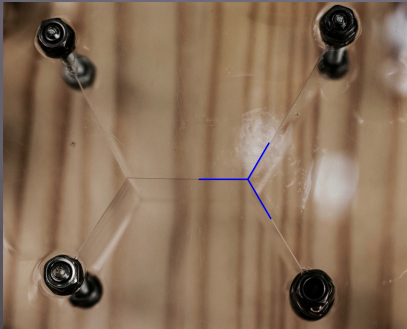
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Minimizers are networks  
without loops  
composed of straight segments  
meeting at triple junctions  
forming angles of  $120^\circ$

# Steiner Problem

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Steiner Problem: Find a connected set  $K$  such that  $\mathcal{L} \subset K$  and the length of  $K$  is minimal

Minimizers are not necessary unique



# Networks

A network can be seen as a couple  $\mathcal{N} = (G, \Gamma)$

where  $G$  is an "abstract graph" with some identifications

and  $\Gamma: G \rightarrow \mathbb{R}^2$  is a map  
 $\Gamma = (\gamma^1, \dots, \gamma^m)$



A network is **degenerate** if  $\exists i \in \{1, \dots, m\}$  such that  $L(\gamma^i) = 0$

A network composed of straight segments that meet at triple junctions forming angles of  $120^\circ$  is called **minimal**



Minimal networks are local minimizers

Minimal networks are local minimizers of the length functional





# Minimal networks are local minimizers

Minimal networks are local minimizers of the length functional

in the sense that

if  $\mathcal{N}_* = (G, \Gamma_* = (\gamma_*^1, \dots, \gamma_*^N))$  is a minimal network

then there exists  $\delta > 0$  such that

$$L(\mathcal{N}) \geq L(\mathcal{N}_*)$$

whenever  $\mathcal{N} = (G, \Gamma = (\gamma^1, \dots, \gamma^N))$

is a triple junction network

such that  $\|\gamma^i \cdot \sigma^i - \gamma_*^i\|_{C^0} < \varepsilon$



# Fixed topology

The minimizers have at most  $m = m - 2$  triple junctions.

Once we fix the topology (we fix the underlying graph  $G$ ) the problem reduces to determine the location of the triple junctions  $x_1, \dots, x_m \in \mathbb{R}^2$

$$\inf \{ \mathcal{L}(x_1, \dots, x_m) = \sum |x_i - p_i| + \sum |x_i - x_j| \mid x_1, \dots, x_m \in \mathbb{R}^2 \}$$

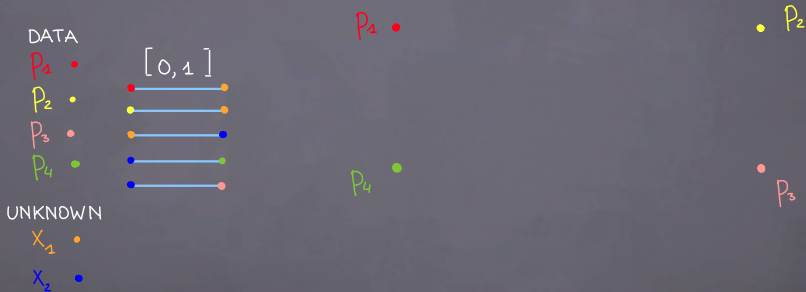
The problem is convex. Existence of minimizer is trivial.

Minimizers can be degenerate

# Fixed topology

Minimizers can be degenerate

Example :



$$\text{inf} \{ \mathcal{L}(x_1, x_2) = |x_1 - P_1| + |x_1 - P_2| + |x_2 - P_3| + |x_2 - P_4| + |x_1 - x_2| \}$$

with  $x_1, x_2 \in \mathbb{R}^2$

# Fixed topology

Minimizers can be degenerate

Example :

DATA

$P_1$  •

$P_2$  •

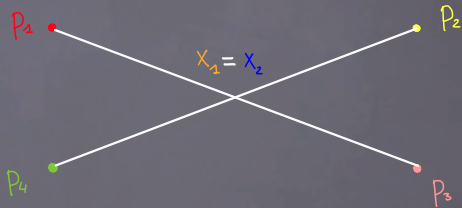
$P_3$  •

$P_4$  •

UNKNOWN

$X_1$  •

$X_2$  •



$$\text{inf} \{ \mathcal{L}(x_1, x_2) = |x_1 - P_1| + |x_1 - P_2| + |x_2 - P_3| + |x_2 - P_4| + |x_1 - x_2| \}$$

with  $x_1, x_2 \in \mathbb{R}^2$  }

# Fixed topology

The minimizers have at most  $m-2$  triple junctions.

Once we fix the topology (we fix the underlying graph  $G$ ) the problem reduces to determine the location of the triple junctions

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The problem is convex. Existence of minimizer is trivial.

The number of possible topologies is finite

Minimize among all minimizers with fixed topology

Difficulty the number of possible topologies escalates as the number of points  $p_1, \dots, p_m$  increases

# Minimal partitions

Let  $n \in \mathbb{N}$  and let  $\Omega \subseteq \mathbb{R}^2$  be an open set.

We say that  $E = (E_1, \dots, E_m)$  is a Caccioppoli partition of  $\Omega$  if

$E_i \subseteq \Omega$ ,  $|E_i \cap E_j| = 0$ ,  $|\Omega \setminus \bigcup_{i=1}^m E_i| = 0$  and  $\mathcal{P}(E_i, \Omega) < +\infty$ .

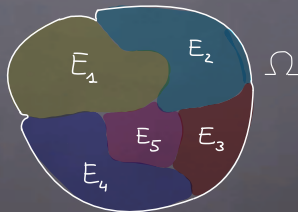


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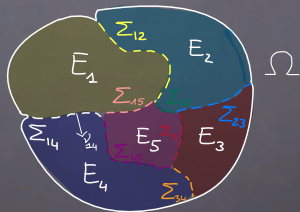
$$E_i \subseteq \Omega, |E_i \cap E_j| = 0, |\Omega \setminus \bigcup_{i=1}^m E_i| = 0 \text{ and } \mathcal{P}(E_i, \Omega) < +\infty.$$

We denote by  $\Sigma_{ij} = (\partial^* E_i \cap \partial^* E_j)$

$\nu_i$  outer outward normal to  $E_i$

$\nu_{ij} = \nu_i = -\nu_j$  unit normal to  $\Sigma_{ij}$  pointing from  $E_i$  to  $E_j$

$$\mathcal{P}(\mathbf{E}) = \frac{1}{2} \sum_{i=1}^m \mathcal{P}(E_i, \Omega)$$





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Minimal partitions problem : given  $\tilde{\mathbf{E}} = (\tilde{E}_1, \dots, \tilde{E}_m)$  find

$\inf \{ \mathcal{P}(\mathbf{E}) : \mathbf{E} = (E_1, \dots, E_m) \text{ Caccioppoli partition of } \Omega$   
such that  $\text{tr}_{\Omega} \chi_{E_i} = \text{tr}_{\Omega} \chi_{\tilde{E}_i} \}$

# Equivalence of Steiner and Minimal Partitions Problem

Let  $\Omega$  be convex.

There exists a minimizer to the Minimal partitions problem.

Ambrosio - Braides  
Morel - Solimini  
Brakke  
Amato - Bellettini - Paolini  
Carioni - Pluda

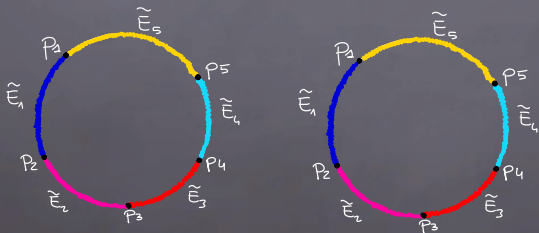
# Equivalence of Steiner and Minimal Partitions Problem

Let  $\Omega$  be convex.

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Let  $\mathcal{L} = \{p_1, \dots, p_n\}$  be a finite collection of points on the boundary of  $\Omega \subset \mathbb{R}^2$  convex.

Then the Steiner Problem and the Minimal partitions problem are equivalent.



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# Paired Calibrations

Let  $\Omega \subseteq \mathbb{R}^2$  be an open set.

A paired calibration for a Caccioppoli partition  $E = (E_1, \dots, E_m)$  is a collection of  $n$  approximately regular vector fields  $\Phi_1, \dots, \Phi_m : \overline{\Omega} \rightarrow \mathbb{R}^2$  such that

$$1) \operatorname{div} \Phi_i = 0$$

$$2) |\Phi_i - \Phi_j| \leq 1 \quad \mathcal{H}^1\text{-a.e. in } \Omega$$

$$3) (\Phi_i - \Phi_j) \cdot \nu_{ij} = 1 \quad \mathcal{H}^1 \text{ a.e. in } \Sigma_{ij}$$

Lawlor-Morgan

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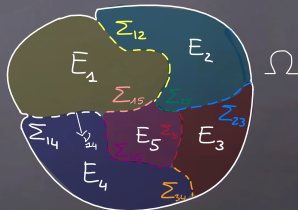
$$3) (\Phi_i - \Phi_j) \cdot \nu_{ij} = 1 \quad \mathcal{H}^1 \text{ a.e. in } \Sigma_{ij}$$

If  $\Phi = (\Phi_1, \dots, \Phi_m)$  is a paired calibration for  $E = (E_1, \dots, E_m)$  then  $E = (E_1, \dots, E_m)$  is a minimizer for the minimal partitions problem

Lawlor-Morgan

# Calibration implies minimality

$$\begin{aligned}
 \mathcal{P}(\tilde{\mathbf{E}}) &= \frac{1}{2} \sum_{i=1}^m \mathcal{P}(\tilde{E}_i, \Omega) = \sum_{i,j} \mathcal{H}^1(\tilde{\Sigma}_{ij} \cap \Omega) + \mathcal{H}^1(\Sigma_{m+1} \cap \Omega) \\
 &= \sum_{i,j} \int_{\tilde{\Sigma}_{ij} \cap \Omega} 1 \, d\mathcal{H}^1 \stackrel{\mathbf{3}}{=} \sum_{i,j} \int_{\tilde{\Sigma}_{ij} \cap \Omega} (\Phi_i - \Phi_j) \cdot \nu_{ij} \, d\mathcal{H}^1 \\
 &= \sum_{i=1}^m \int_{\Omega} \Phi_i \cdot \mathcal{D}\chi_{\tilde{E}_i} \stackrel{\mathbf{1}}{=} \sum_{i=1}^m \int_{\Omega} \Phi_i \cdot \mathcal{D}\chi_{E_i} \\
 &= \sum_{i,j} \int_{\Sigma_{ij} \cap \Omega} (\Phi_i - \Phi_j) \cdot \nu_{ij} \, d\mathcal{H}^1 \\
 &\stackrel{\mathbf{2}}{\leq} \sum_{i,j} \int_{\Sigma_{ij} \cap \Omega} |\Phi_i - \Phi_j| \, d\mathcal{H}^1 \leq \sum_{i,j} \mathcal{H}^1(\Sigma_{ij} \cap \Omega) \\
 &= \frac{1}{2} \sum_{i=1}^m \mathcal{P}(E_i, \Omega) = \mathcal{P}(\mathbf{E})
 \end{aligned}$$





## Looking at the differences

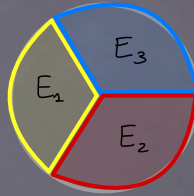
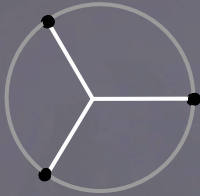
Given a Caccioppoli partition  $E = (E_1, E_2, E_3)$  and the vector fields  $\Psi_{12}, \Psi_{23}, \Psi_{31} : \overline{\Omega} \rightarrow \mathbb{R}^3$  such that  $\operatorname{div} \Psi_{ij} = 0$ ,  $|\Psi_{ij}| \leq 1$ ,  $\Psi_{ij} \cdot \nu_{ij} = 1$   $\mathcal{H}^1$  a.e. in  $\Sigma_{ij}$  and with the property that  $\Psi_{12} + \Psi_{23} + \Psi_{31} = 0$ , the collection of vector fields defined by  $\Phi_1 = (0, 0, 0)$ ,  $\Phi_2 = -\Psi_{12}$ ,  $\Phi_3 = \Psi_{31}$  is a calibration for  $E = (E_1, E_2, E_3)$ .

# Example : calibration of the triple junction

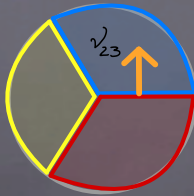
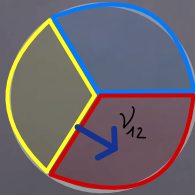
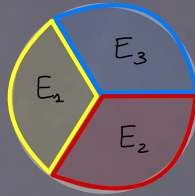
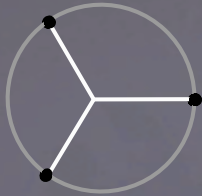


Lawlor-Morgan

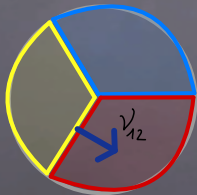
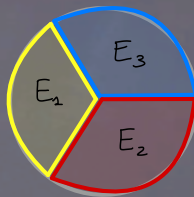
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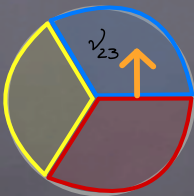
# Example : calibration of the triple junction



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$$\overline{\Psi}_{12} = v_{12}$$



$$\overline{\Psi}_{23} = v_{23}$$



$$\overline{\Psi}_{31} = v_{31}$$

# Example of non-existence of calibration

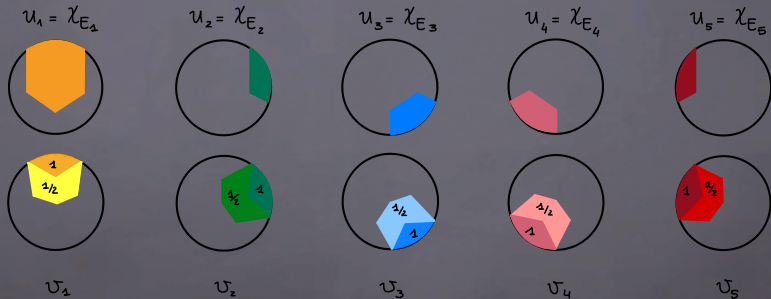
"Caccioppoli partition  $E = (E_1, \dots, E_m)$ " is equivalent to  
"collection of  $m$  functions  $u_i \in BV(\Omega, \{0, 1\})$  with  $u_i = \chi_{E_i}$ ."

If  $\Phi = (\Phi_1, \dots, \Phi_m)$  is a paired calibration for  $u_1, \dots, u_m \in BV(\Omega, \{0, 1\})$   
then the collection  $u_1, \dots, u_m$  minimize  $\sum_{i=1}^m |Du_i|(\Omega)$   
among all collections of  $m$  functions  $v_i \in BV(\Omega, [0, 1])$   
with a finite number of values  $d_1, \dots, d_k$ , such that  
 $\sum_{i=1}^m v_i(x) = 1$  for a.e.  $x \in \Omega$  and  $\int_{\Omega} u_i = \int_{\Omega} v_i$

Bonafini-Orlandi-Oudet  
Carioni-Pluda

# Example of non-existence of calibration

"Caccioppoli partition  $E = (E_1, \dots, E_m)$ " is equivalent to  
"collection of  $m$  functions  $u_i \in BV(\Omega, \{0, 1\})$  with  $u_i = \chi_{E_i}$ "



# A local minimality result

Let  $\mathcal{N}$  be a minimal network contained in  $D$  homeomorphic to a closed disk and with endpoints  $p_1, \dots, p_m \in \partial D$

Then there exists a bounded open set  $\Omega$  and  $E = (E_1, E_2, E_3)$  a Caccioppoli partition of  $\Omega$  such that  $\mathcal{N} = \Omega \cap \bigcup_{i=1}^3 \partial^* E_i$

Moreover there exists a paired calibration for  $\mathcal{N}$  in  $\Omega$

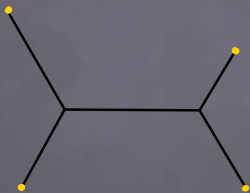
In particular  $E$  is a minimizer of  $\int_{\Omega} |D\phi|$  among all  $E'$  having the same trace of  $E$  on  $\partial\Omega$

Pluda-Pozzetta



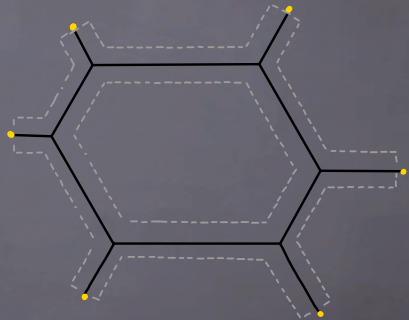
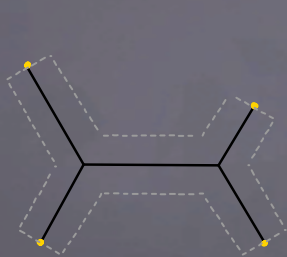
# Proof

Prototypical configurations :



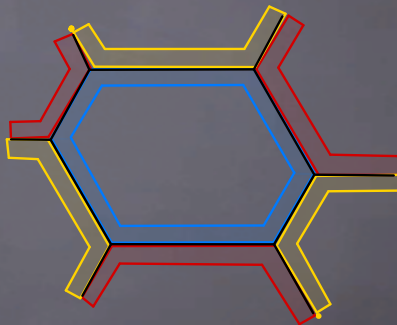
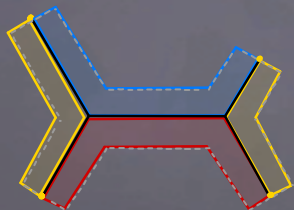
# Proof

We take a truncated  $\delta$ -neighborhood

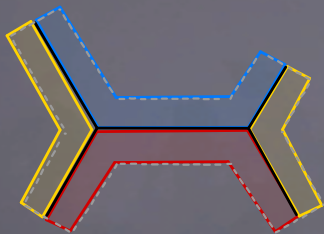


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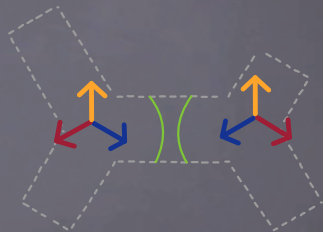
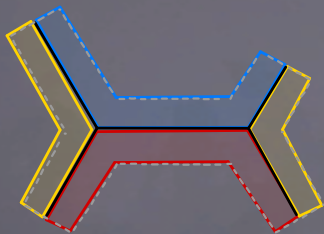
We define the partition



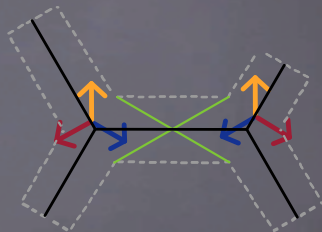
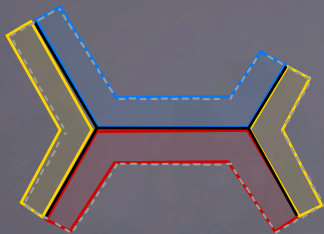
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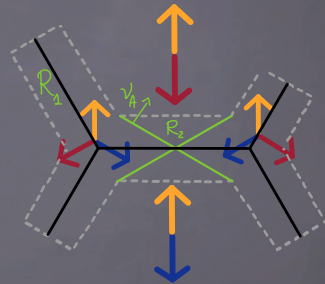
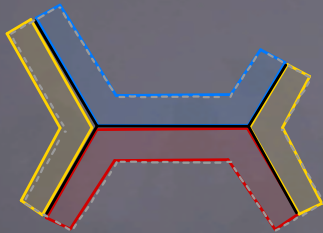
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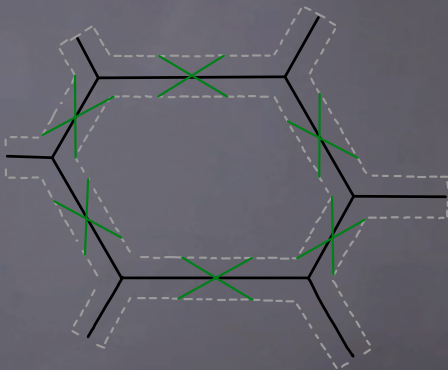
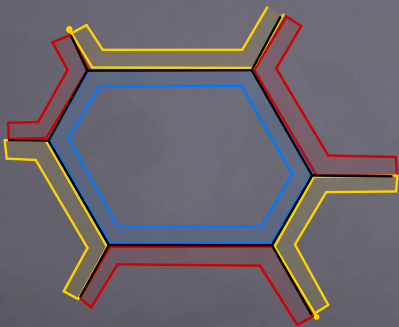


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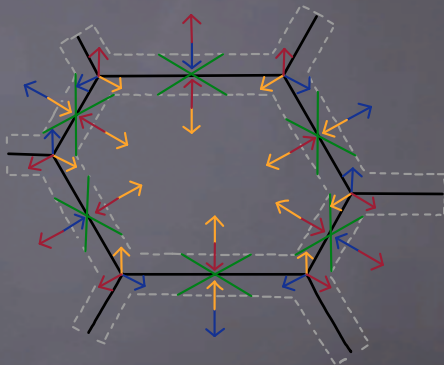
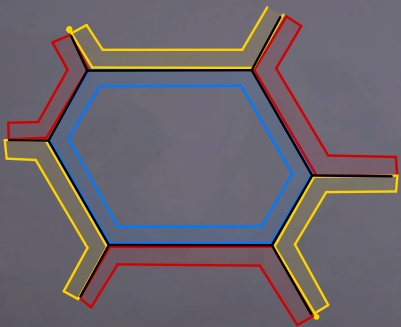
$$\text{tr}_{R_1}(\Psi_{ij}|_{R_1}) \cdot v_A = -\text{tr}_{R_2}(\Psi_{ij}|_{R_2}) \cdot v_A$$

# Proof





# Proof



## Currents with coefficients in $\mathbb{R}^m$

A 1-form  $\omega$  with values in  $\mathbb{R}^m$  is an array  $\omega = (\omega_1, \dots, \omega_m)$  of 1-forms

$C_c^\infty(\mathbb{R}^2, \Lambda_m^1(\mathbb{R}^2))$  is the space of 1-forms with values in  $\mathbb{R}^m$

A 1-current with coefficients in  $\mathbb{R}^m$  is a linear and continuous map  $T: C_c^\infty(\mathbb{R}^2, \Lambda_m^1(\mathbb{R}^2)) \rightarrow \mathbb{R}$

Its mass is defined as

$$M(T) := \sup \{ T(\omega) : \omega \in C_c^\infty(\mathbb{R}^2, \Lambda_m^1(\mathbb{R}^2)) \text{ with } \|\omega\|_{\text{com}} \leq 1 \}$$

and its boundary is the 0-current defined by

$$\partial T(\omega) = T(d\omega) \quad \forall \omega \in C_c^\infty(\mathbb{R}^2, \Lambda_m^1(\mathbb{R}^2))$$

Fleming, White

# A mass-minimization problem

Let  $\{g_1, \dots, g_{m-1}\}$  be the canonical base of  $\mathbb{R}^{m-1}$  and  $g_m := -\sum_{i=1}^{m-1} g_i$

We define a norm  $\|\cdot\|$  on  $\mathbb{R}^{m-1}$  in such a way that given  $\mathcal{I}$  any subset of  $\{1, \dots, m-1\}$  it holds  $\|\sum_{i \in \mathcal{I}} g_i\| = 1$

Given  $\{p_1, \dots, p_m\}$  a finite collection of points in  $\mathbb{R}^2$  we define the 0-current  $\mathcal{B} = g_1 \delta_{p_1} + \dots + g_m \delta_{p_m}$

Problem (\*):

$\text{inf} \{ M(T) : T \text{ 1-rectifiable current with coefficients in } \mathbb{Z}^{m-1}, \partial T = \mathcal{B} \}$ .

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$g_1 \cdot$

$\bullet -g_1 - g_2 - g_3 - g_4$

$\bullet g_4$

$g_2 \cdot$

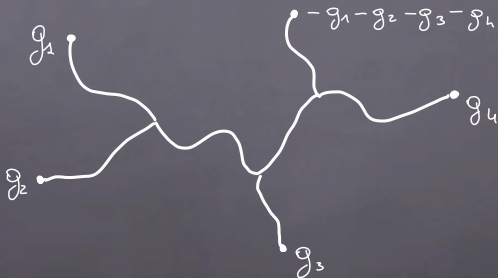
$\bullet g_3$

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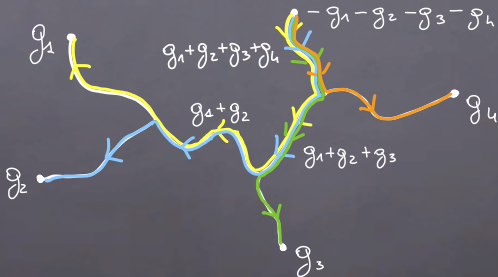


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# Equivalence of Steiner and the mass minimization Problem

There exists a minimizer to the mass-minimization problem (\*)

Marchese - Massaccesi

# Equivalence of Steiner and the mass minimization Problem

There exists a minimizer to the mass-minimization problem (\*)

The Steiner Problem and the mass-minimization problem (\*) are equivalent.

Marchese - Massaccesi



# Calibrations for $\mathcal{G}$ -currents

Let  $\mathcal{G}$  be a normed subgroup of  $\mathbb{R}^{m-1}$

Let  $T = [\Sigma, \tau, \theta]$  be a 1-rectifiable current with coefficients in  $\mathcal{G}$  and  $\omega \in C_c^\infty(\mathbb{R}^2, \Lambda_m^1(\mathbb{R}^2))$

Then  $\omega$  is a calibration for  $T$  if

1)  $d\omega = 0$

2)  $\|\omega\|_{\text{com}} \leq 1$

3)  $\langle \omega(x)\tau(x), \theta(x) \rangle = \|\theta(x)\|$  for  $\mathcal{H}^1$ -a.e.  $x \in \Sigma$

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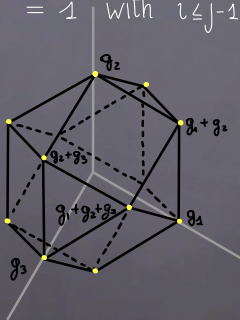
If  $\omega$  is a calibration for  $T$   
then  $T$  is mass minimizing in its homology class

# Equivalence of calibrations

Let  $\{g_1, \dots, g_{m-1}\}$  be the canonical base of  $\mathbb{R}^{m-1}$  and  $g_m := -\sum_{i=1}^{m-1} g_i$

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$$\left\| \sum_{k=i}^{j-1} g_k \right\| = 1 \quad \text{with } i \leq j-1 \quad i, j \in \{1, \dots, m\}$$



Carioni-Pluda

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Then there exists a permutation of the labelling of the points  $p_1, \dots, p_m$  such that gives the equivalence of the paired calibrations and the calibrations for  $G$ -currents

Carioni-Pluda

# From minimal networks to $G$ -currents

Let  $g_1 = (1, 0)$ ,  $g_2 = (-\frac{1}{2}, -\frac{\sqrt{3}}{2})$  and  $g_3 = -g_1 - g_2$ .

We choose a norm  $\|\cdot\|$  on  $\mathbb{R}^2$  such that

$$\|g_1\| = \|g_2\| = \|g_1 + g_2\| = 1$$

Let  $\widehat{G}$  be the discrete group generated by  $g_1$  and  $g_2$  w.r.t. addition

Pluda-Pozzetta

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Let  $\widehat{\mathcal{G}}$  be the discrete group generated by  $g_1$  and  $g_2$  w.r.t. addition

There is a canonical way to associate to  $\widehat{\mathcal{N}}$  minimal network a 1-rectifiable current  $\widehat{T} = [\widehat{\Sigma}, \widehat{\tau}, \widehat{\theta}]$  with coefficients in  $\widehat{\mathcal{G}}$  such that

$$\text{supp}(\widehat{T}) = \widehat{\mathcal{N}} \quad \mathbb{L}(\widehat{\mathcal{N}}) = \mathbb{M}(\widehat{T})$$

and  $\widehat{B} = \partial \widehat{T} = c_1 \delta_{p_1} + \dots + c_m \delta_{p_m}$  with  $c_i \in \{\pm g_1, \pm g_2, \pm g_3\}$

Pluda-Pozzetta

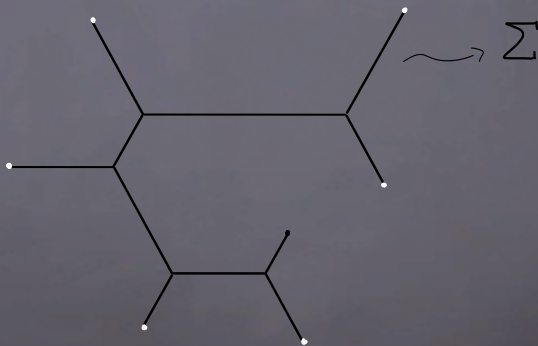
# From minimal networks to $\mathcal{G}$ -currents

There is a canonical way to associate to  $\hat{\mathcal{N}}$  minimal network a  $\mathbb{1}$ -rectifiable current  $\hat{T} = [\hat{\Sigma}, \hat{\tau}, \hat{\theta}]$  with coefficients in  $\hat{\mathcal{G}}$



# From minimal networks to $\mathcal{G}$ -currents

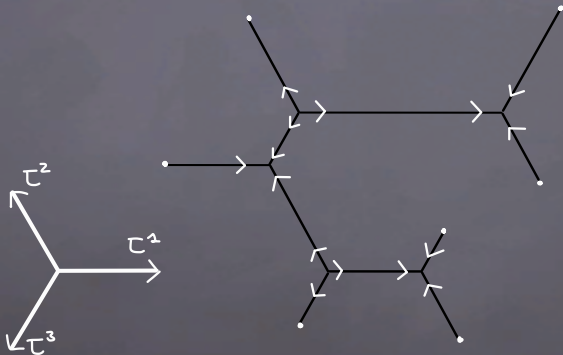
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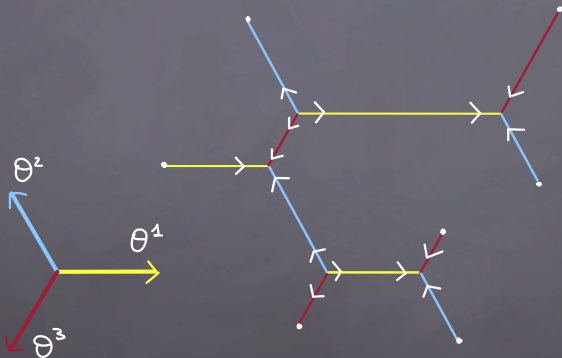
# From minimal networks to $\mathcal{G}$ -currents

There is a canonical way to associate to  $\hat{\mathcal{N}}$  minimal network a  $\tau$ -rectifiable current  $\hat{T} = [\hat{\Sigma}, \hat{\tau}, \hat{\theta}]$  with coefficients in  $\hat{\mathcal{G}}$



# From minimal networks to $\mathcal{G}$ -currents

There is a canonical way to associate to  $\widehat{\mathcal{N}}$  minimal network a  $\mathbb{1}$ -rectifiable current  $\widehat{T} = [\widehat{\Sigma}, \widehat{\tau}, \widehat{\theta}]$  with coefficients in  $\widehat{\mathcal{G}}$



## A global minimality result

There exists a calibration for the 1-rectifiable current  $\hat{T}$  with coefficients in  $\hat{G}$  canonically associated to  $\hat{N}$  minimal network. In particular  $\hat{T}$  is mass minimizing among 1-normal currents with coefficients in  $\mathbb{R}^2$  with and with boundary  $\hat{B}$ .

Pluda-Pozzetta

## A global minimality result

There exists  $\omega$  calibration for the 1-rectifiable current  $\hat{T}$  with coefficients in  $\hat{G}$  canonically associated to  $\hat{N}$  minimal network. In particular  $\hat{T}$  is mass minimizing among 1-normal currents with coefficients in  $\mathbb{R}^2$  with and with boundary  $\hat{B}$ .

$$\text{Take } \omega = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Pluda-Pozzetta

# Łojasiewicz-Simon inequality

Let  $\mathcal{N}_* = (G, (\gamma_*^1, \dots, \gamma_*^N))$  be a minimal network.

Then there exists  $c > 0$ ,  $\varepsilon > 0$ ,  $\theta \in (0, \frac{1}{2}]$  such that the following holds

if  $\mathcal{N} = (G, (\gamma_0^1, \dots, \gamma_0^N))$  is a regular network such that

$$\sum \|\gamma_0^i - \gamma_*^i\|_{H_2} < \varepsilon$$

Then

$$|L(\mathcal{N}) - L(\mathcal{N}_*)|^{1-\theta} \leq c \left( \sum_i \int_0^1 |\vec{k}|^2 ds \right)^{1/2} = c \|\vec{k}_{\mathcal{N}}\|_2$$